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SKY LUMINANCE DATA VALIDATION: COMPARISON OF SEVEN MODELS WITH FOUR DATA BANKS

PIERRE INEICHEN,*† BENOÎT MOLINEAUX,* and RICHARD PEREZ**†
*University of Geneva, GAP, 1231 Conches, Switzerland
**ASRC, State University of New York, Albany, NY, U.S.A.

Abstract—In order to insure the comparability of the data acquired within the International Daylight Measurement Program, we made a preliminary investigation on the behavior of four daylight data banks when compared with the predictions of seven sky luminance distribution models. We present, in this study, the results of these comparisons, focusing on the performance of the models depending on the site of measurements, the position of the point source of light within the sky, and the weather conditions. We obtain on the whole very similar results, independently of the instrument and the site of measurement, even with limited data banks that cannot be taken as representative of the various climates.

1. INTRODUCTION

In the field of interior design, a good knowledge of the energy and daylight availability is essential for an efficient use of these renewable resources. Solar radiation is measured in many stations throughout the world; this is not the case for daylight. In order to provide for this lack of data, the "Commission Internationale de l'Eclairage" (CIE) has organized an International Daylight Measurement Program (IDMP) with the objective of collecting worldwide data on daylight availability. In January 1993, IDMP regrouped 15 "research class stations" [21] around the world: 5 in Europe, 5 in Japan, 2 in the U.S., 2 in Asia, and 1 in Australia. We operate one such a station in Geneva, Switzerland, where we measure irradiance (global, diffuse, and beam), illuminance (global, diffuse, beam, and vertical) and luminance (zenith, sky).

The development and evaluation of luminous efficacy and sky luminance distribution models require measured values that are severely tested and validated. To achieve this goal, Molineaux and Ineichen [14] developed an effective automatic quality control procedure.

In this article, we are concerned with the performance of sky luminance models and with the quality of the data used for their evaluation. We present a preliminary investigation on the behavior of daylight data banks from four different countries when compared to the predictions of seven models. The results give a good idea of the quality and comparability of the daylight measurements being collected within IDMP, in view of a large-scale exchange of data.

2. DESCRIPTION OF THE SITES

We obtained a limited set of data from three other laboratories in Japan, the U.S., and Great Britain, For

each data bank, we give, in Table 1, the location of the station, the number of days involved in this study, the time step of the acquisition, the measured parameters, and the type and manufacturer of the sensors. The measurements are independent (different manufacturers, different calibration of sensors, different methods of measurement, etc.) and cover a period of approximately 10 days with clear, intermediate, and overcast conditions. For Geneva, we chose a 9-day period in August 1992.

Data from Japan

The station is located in Koto-Ku, at Takenaka Corporation, Technical Research Laboratories. All the Japanese instruments are manufactured by EKO in Japan. The data bank includes 8 days of data, from May 12 to May 21, 1992. The measurements are taken every 30 min and are instantaneous values. The scan duration is 2 min 35 s; irradiances and illuminances are measured at the beginning of the scan [5].

Data from the U.S.

The data set was taken at Battelle Institute, Berkeley in 1985 and 1986 by J. Michalsky *et al.* [13] and reactualized by R. Perez *et al.* [16] at ASRC (Albany). The sky scanner is a homemade instrument by Kleckner *et al.* [8]; one scan consists of 186 points of measurement. Only the beam illuminance was simultaneously recorded during the data acquisition. The other illuminance and irradiance components are integrals or modeled values. We used 11 days of data from September 16 to September 31, 1985.

Data from Great Britain

The city of Garston is located 30 km northwest of London; the station is at the BRE (Building Research Establishment) and under the responsibility of P. Littlefair. As in Geneva, their sky scanner is manufactured by PRC Krochmann (During the analysis of BRE's

[†] ISES members

Table 1. Data banks; location of the station, number of days involved in this study, time step of the acquisition, measured parameters, and type and manufacturer of the sensors

Country	Japan	U.S.A.	Great Britain	Switzerland
City	Koto-Ku	Berkeley	Garston	Geneva
Institute	Takenaka Corp.	LBL	BRE	University
Latitude	35.7°N	37.9°N	51.7°N	46.2°N
Longitude	139.8°E	122.2°W	0.4°W	6.1°E
Altitude	22 m	396 m	80 m	400 m
Sky scanner	EKO	MASP (Battelle)	PRC Krochmann	PRC Krochmann
No. pts. per scan	145	186	145	145
No. days/no. scans	8/203	11/423	9/257	9/376
Time step	30'	15'	15'	15'
Dvh	EKO ML-010S	Scan integral	LMT	LiCor
Bvn	EKO ML-010SD	Sun luminance	LiCor + NIP tube	LiCor + NIP tube
Gvh	EKO ML-010S	$Dvh + Bvn \sin(hs)$	LMT	PRC 910GV
Bn	EKO MS-52	Luminous efficacy	NIP	NIP
Gh, Dh	EKO MS-801	Luminous efficacy	CM11	CM11
Diffuse	Shadow band 5/50	Scan integral	Shadow band 5/50	Rotating disk
Vertical irradiances	NESW	ra Tass our munital rated to	NESW	og gal, alno <u>m</u>
Vertical illuminances	NESW	reservations and to servab	NESW	NESW

data, Littlefair [11] noted the same problems as we had with our scanner described by Ineichen and Molineaux [14]). The diffuse components are measured with a 50 mm \times 508 mm shadow band and are corrected using skies with nonuniform luminance distribution, including the CIE overcast and clear skies [11]. We have 9 days of data from August 20, 1991 to January 15, 1992.

Data from Geneva

To use a comparable set of data, we extracted from our data bank a 9-day data set from August 22, 1992 to September 1, 1992. Our instrument is a PRC sky scanner and we are recording instantaneous values every 15 min. The duration of the scan is 30 s and we are measuring the illuminance and irradiance components during the first 15 s of the scan. Our sensors are calibrated outdoors side by side against a LiCor and a CM10 substandard, which are calibrated, respectively, at the Institut de Métrologie (Berne, Switzerland) and at the World Radiation Centre (WRC, Davos, Switzerland).

3. INTERCOMPARISON OF THE DATA

The first step of our analysis was to test the coherence of the data. We compared the horizontal diffuse illuminance, Dvh, with the integral of the luminances over the hemisphere. For the integral, we took into account all luminance measurements for which the distance to the sun was greater than 6° (respectively, 144 and 185 measurements/scan). Considering that illuminances are easier to measure, and illuminance sensors easier to calibrate, we made the hypothesis that the value of Dvh was correct if the three basic illuminances (direct, global, and diffuse) were coherent with each other. As we noted some disparity between Dvh and the scan integral, we normalized the integral of the scan to the corresponding diffuse horizontal illuminance.

4. DESCRIPTION OF THE SKY LUMINANCE DISTRIBUTION MODELS

All the models used in this study (except the Perez model) are summarized in a publication from Perez *et al.* [17], Table 2 gives the input data, the governing parameters, etc., for each model.

Brunger model

The model is a three-component continuous model and was originally developed for modeling the sky radiance; it is a superposition of three distinct terms, isotropic, circumsolar, and horizontal brightening factor. The weighting parameters are Dh/Gh and the clearness index Kt [2].

Matsuzawa model

This model is a combination of the three CIE standard skies: clear, intermediate, and overcast. The governing parameter is an illuminance "cloud ratio" defined as *Dvh/Gvh* [12].

ASRC-CIE model

Perez et al. [17] modified Matsuzawa's model to take into account the high turbid intermediate skies. The interpolating parameters are Perez' epsilon and delta (clearness and brightness) coefficients. We reference here two versions of the model [15,17]; the best results are obtained with the most recent version, which was used in this study.

Perez model

Five coefficients describe the quality and the quantity of the luminance of the sky dome. Each of the coefficients has a specific physical effect and depends on epsilon and delta: (a) darkening or brightening of the horizon region; (b) luminance gradient near the horizon; (c) relative intensity of the circumsolar region; (d) width of the circumsolar region; and (e) the relative backscattered light [18].

Table 2. Sky luminance distribution models: Summary of the input data, governing parameters, and number of coefficients

Model	Input	Geometry	Weighting parameter	Coefficients matrix
Brunger	Gh, Dh, Dvh	Z, Io	K, Kt	$4 \times (9 \times 9) = 324$
Matsuzawa	Gvh, Dvh	Z	Kv	_
			CIE skies	
ASRC-CIE	Gh, Bn	Z, Io	Epsilon, delta	
			CIE skies	
Perez	Gh, Bn	Z, Io	Epsilon, delta	$5 \times (8 \times 4) = 160$
Perraudeau	Gh, Dh	Z	Nebulosity index	$5 \times 8 = 40$
Kittler	Bvn, albedo	Z, Ivo, Ma	Illum. turbidity	_
Harrison	Opaque cloud cover (Gh, Dh)*	Z	Op. cloud cover (normalized K)*	18 -

^{*} When op. cloud cover not available. Kt = clearness index; K = Dh/Gh; Kv = Dvh/Gvh.

Perraudeau model

The formulation of the model is a product of three functions, depending respectively on the angular distance to the sun (zeta), the height of the considered point, and the sun height. The five discrete sky conditions are parameterized with a nebulosity index, which is a normalized cloud ratio [20].

Harrison model

The Harrison model needs an opaque cloud cover [3] to combine two basic luminance distributions: clear and cloudy sky. We used a normalized Dh/Gh coefficient as opaque cloud cover.

Kittler model

Based on the light diffusion theory, the Kittler [9] model is a complex formula that calculates the absolute or relative sky luminance pattern. The governing parameter is the atmospheric illuminance turbidity.

5. COMPARING THE MODELS

The performance of each model is evaluated with the mean bias difference:

$$MBD = \frac{1}{N} \cdot \sum_{i=1}^{N} (computed value_i - measured value_i)$$

and the root mean square difference:

RMS

$$= \sqrt{\frac{1}{N} \cdot \sum_{i=1}^{N} (\text{computed value}_{i} - \text{measured value}_{i})^{2}}$$

both expressed in relative values (%). We used two methods to compare the performances of the models described above:

Relative comparison: in this case, the sum or the
average of the evaluated sky luminance points is
normalized by a corresponding measured value. The
mean bias difference (MBD) will always be zero.
Considering the points near the horizon are as important as the points near the zenith (if one considers
a vertical surface, the luminance from the zenith re-

gion becomes negligible) we normalize the calculated values with an average luminance (and not an integrated illuminance).

 Absolute comparison: for these comparisons, we use luminance values expressed in cd·m⁻² and normalized by Dvh. The result will be a nonzero MBD, depending on the ability of the model to describe the climate.

In Table 3 we give the number of occurrences in the data banks involved in this study for each model parameter, for the sun height and Linke turbidity coefficient.

All sky performance

We first analyzed the behavior of the models with the available parameters. Fig. 1 represents the behavior of the models with 12 geometrical and meteorological parameters. Each figure represents the difference between computed and measured values (C-M) expressed in $\operatorname{cd} \cdot \operatorname{m}^{-2}$ versus the considered parameter. The abscissa is divided into bins; for each of them we represent the MBD (point) surrounded by ± 1 standard deviation (SD) (line):

$$SD = \sqrt{\frac{1}{N-1} \cdot \sum_{i=1}^{N} \left[(C-M)_i - \overline{(C-M)} \right]}$$

All the calculated values are normalized by the mean luminance (relative comparison); we did not take into account the points near the horizon (6° of elevation for Koto-Ku, Garston, and Geneva; 10° for Berkeley) because of the nonuniformity of the horizon.

One can point out that, although the different models do not have the same overall performance, the dependence patterns are very similar and show that the bias becomes greater near the sun (cf. pt. azimuth, zeta, Lvm dependence graphs). All of these models were developed for values of zeta (angular distance between the considered point and the sun) greater than about 12° to 15°. It should also be noted that some of the error may be attributed to the instruments' nonzero field of view; because of the steep luminance gradient near the sun, and because of the possible stray light, the instrument will have a tendency to overestimate for points close to the sun's position.

 $0.7 \rightarrow 0.8$ 193 $0.2 \rightarrow 0.3$ 133Bin 8 Table 3. Number of occurrences of different sky conditions for the model parameters, sun height, and Linke turbidity coefficient $0.6 \rightarrow 0.7$ 152 $0.3 \rightarrow 0.4$ 102 $4.5 \rightarrow 6.2$ 117 $0.5 \rightarrow 0.6$ 115 $0.4 \rightarrow 0.5$ $2.8 \rightarrow 4.5$ 168Bin 6 $1.95 \rightarrow 2.8$ 107 $0.4 \rightarrow 0.5$ $0.5 \to 0.6$ Bin 5 95 $1.5 \rightarrow 1.95$ 81 $0.3 \rightarrow 0.4$ 1420.6 → 0.7 44 Bin 4 $1.23 \rightarrow 1.5$ 55 $0.2 \rightarrow 0.3$ 172 $0.7 \rightarrow 0.8$ Bin 3 $1.065 \rightarrow 1.23$ 39 $0.1 \rightarrow 0.2$ 216 $0.8 \rightarrow 0.9$ 53Bin 2 1 → 1.065 645 $0 \rightarrow 0.1$ 133 $0.9 \rightarrow 1$ 610Bin 1 Perez Epsilon No. of occurrences Brunger

0110	07 - 03	03-004	0.4 - 0.5	30 - 30	20. 30	07 - 00	00 00
0.1 10.2	0.2 \$ 0.3	4.0 1.0	0.4 + 0.3	0.0 + 0.0	0.0 10.1	0.7 \$ 0.8	0.8 \$ 0.5
216	172	142	95	115	152	193	41
0.8 → 0.9	0.7 → 0.8	0.6 → 0.7	0.5 → 0.6	0.4 → 0.5	0.3 → 0.4	$0.2 \rightarrow 0.3$	0.1 → 0.2
53	37	44	46	75	102	133	159
1.4 → 3	3 ↑ 6	1 9					
237	250	55					
0.3 → 0.65	0.65 →						
281	764						
0.05 → 0.2	0.2 → 0.7	0.7 → 0.9	0.9 →				
268	155	151	328				
15° → 25°	25° → 35°	35° → 45°	45° → 55°	55° → 65°	65° → 75°		
218	181	202	287	33	42		
2.25 + 2.75	2.75 → 3.25	3.25 → 3.75	3.75 → 4.25	4.25 → 4.75	4.75 → 5.25	For eps	For epsilon > 6
4	26	13	7	3	0		

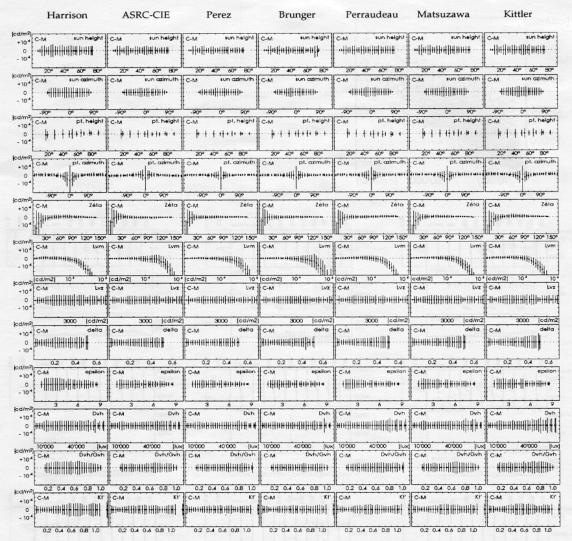


Fig. 1. Performance of seven models versus different parameters for all the stations. The luminance values are normalized by the mean luminance. The pt. azimuth is the angular distance between the azimuth of the point and the azimuth of the sun.

Considering the overall performances, two models give slightly better results: the Perez and Brunger models. We chose these two models for further analysis.

The detailed results obtained with the Perez model and data from all four sites are represented in Fig. 2. On the scatter-plot, one has the calculated values (*Lvc*) versus the corresponding measured values (*Lvm*). The diagonal line is representative of an ideal model. In order to underline the importance of the region near the sun, where the MBD and RMS become significant, we added histograms representing the number of considered points.

Performance in four regions of the sky

Using the MBD and SD indicators, we analyzed the behavior of the models for four different regions in the sky vault:

- the zenith region—all the points higher than 60° above the horizon (pt. height > 60°, ≈20% of the points);
- the "south" region—the region in the direction of the sun (pt. azimuth < 45° and pt. height < 60°, ≈20% of the points);
- the "north" region—the region opposite to the sun region (pt. azimuth > 135° and pt. height < 60°, ≈20% of the points); and
- the "east-west" region—the region on the left-hand side and the right-hand side of the sun $(45^{\circ} < pt.$ azimuth $< 135^{\circ}$ and pt. height $< 60^{\circ}$, $\approx 40\%$ of the points).

For all these cases, we normalize the integrated value of the scan to the diffuse illuminance (*Dvh*); we neither consider points within 15° of the sun, nor the points near the horizon.

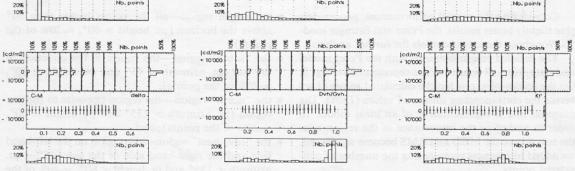


Fig. 2. Performance of the Perez model versus different parameters, for all the hemisphere and the four stations; the calculated luminance values are normalized by Dvh: (A) as in Fig. 1; (B) relative number of points for each of the 33 bins; (C) distribution of the MBD around the ideal model (MBD = 0), and each histogram is a compilation of three of the above bins; and (D) overall histogram of the distribution of the MBD.

Table 4. Mean bias difference (MBD) and root mean square difference (RMS) between model and measurements for the four stations and the seven models, for different normalizations, and cutting value for zeta with and without the horizon points

		Perez	rez	Brunger	ıger	ASRC-CIE	-CIE	Matsuzawa	ızawa	Harrison	ison	Perrandeau	ıdean	Kittler	tler			
Station	Lvm	MBD	RMS	MBD	RMS	MBD	RMS	MBD	RMS	MBD	RMS	MBD	RMS	MBD	RMS	Norm.	Horizon	Zeta
Koto-Ku (203 scans)	1669	2%	48%	2%	45%	3%	53%	3%	57%	5%	48%	14%	65%	2%	58%	Dvh	With	9<
	7820	-2%	44%	-4%	41%	-3%	46%	-3%	53%	-3%	44%	%0	51%	-2%	26%	Dvh	Without	9<
	7820	-	40%	I	37%	1	45%	1	46%	1	40%	d	46%	(2.) (1.) (1.)	53%	Lvm	Without	9<
	7189		27%	1	27%	1	29%	1	31%	1	33%	110 110	38%		37%	Lvm	Without	>15
Berkeley (423 scans)	5493	%0	42%	-3%	48%	%0	45%	-3%	51%	%0	29%	4%	52%	-3%	53%	Dvh	With	9<
	5448	%0	42%	%0	46%	%0	45%	-1%	52%	1%	29%	2%	48%	-1%	55%	Dvh	Without	9<
	5448	1	41%	I,	45%	-1	44%	1	51%	I	%09	ŀ	48%	1	54%	Lvm	Without	9<
343	8805	I	36%	1	39%	1	38%	1	43%	1	42%	1	43%	ı	46%	Тет	Without	>15
Garston (257 scans)	3184	3%	46%	1%	54%	1%	54%	-1%	%19	5%	79%	11%	53%	5%	51%	Doh	With	9<
	2957	4%	45%	4%	48%	2%	54%	2%	62%	4%	74%	7%	47%	4%	51%	Dvh	Without	9<
	2957	1	43%	1	46%	ı	52%	1	%09	1	74%	1	42%	1	48%	Lvm	Without	9<
	2704	1	42%	1	43%	I	47%	1,	52%	1	28%	1	41%	pos H	45%	Lvm	Without	>15°
Geneva (376 scans)	5848	2%	46%	-3%	48%	1%	52%	1%	26%	1%	52%	8%	63%	1%	28%	Doh	With	9<
	2965	-1%	46%	-2%	47%	-2%	46%	-2%	53%	-2%	51%	1%	26%	-2%	26%	Doh	Without	9<
	2962	1	44%	1	45%	1	48%	1	51%	ı	51%	1	51%	ŀ	53%	Lvm	Without	>9<
	5421	1	40%	1	42%	I	42%	1	43%	1	45%		45%	jels Li	46%	Tom	Without	>15
All stations (1259 scans)	5381	2%	46%	-1%	48%	1%	51%	%0	57%	2%	57%	8%	%09	%0	57%	Dvh	With	9<
	5475	%0	46%	-1%	46%	-1%	49%	-1%	55%	%0	55%	2%	53%	-1%	57%	Dvh	Without	9<
	5475	Ī	43%	1	44%	1	47%	1	53%	1	55%	1	20%	l	55%	Lvm	Without	°9<
	5039	1	37%	1	39%	I	39%	1	42%	1	43%	Ī	46%	ı	45%	Lvm	Without	>15°

The results are presented in Table 4. One can see, in this table, that even if some of the models have a bias of approximately zero for the complete sky, this is not the case if we test different regions of the sky separately. The two previously selected models give the best description of the sky vault for all the considered regions.

Note that, as we previously observed, the SD remains high for all models. This is understandable because of the effect of "one-of-a-kind" cloud patterns that cannot be deterministically modeled. However, techniques are being developed to incorporate this "cloud noise" into a realistic model [1, 19].

6. SITE DEPENDENCE OF THE MODELS

Table 4 shows the results obtained when applying the seven models to the four limited data sets, for four different conditions:

The scans are normalized by Dvh and evaluated over

- the whole hemisphere. This represents the overall performance of the model.
- The scans are normalized by *Dvh*, but without taking into account the first series of points above the horizon, in order to eliminate the effect of a nonideal horizon (in Geneva, we have a 6° high mountain in the southeast direction).
- The scans are normalized by the mean value of Lvm (MBD is zero), without the horizon. This is the intrinsic performance of the model.
- The same as above, but with cutting the points that are within 15° from the sun. This shows the circumsolar region influence on the model.

Fig. 3 is a graphical representation of the site dependence of Brunger's model. The graphs representing the dependence with the relative azimuth of the considered point (pt. azimuth) show a significant degradation of the MBD and the SD for the station of Garston and Geneva near the sun position (0° on the graphs). Concerning the data from Geneva, we know that the in-

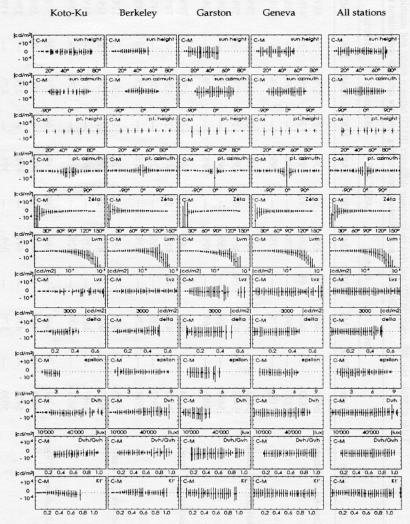
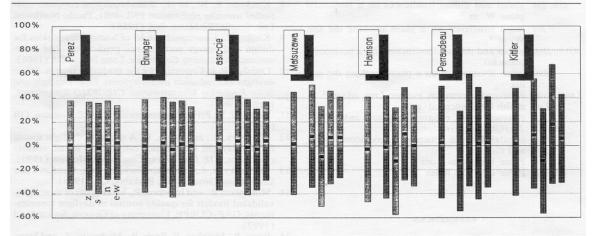


Fig. 3. Performance of the Brunger model versus different parameters, for the four stations; the luminance values are normalized by the mean luminance.

Table 5. Histograms of the models' performances for different sky regions. The first bar represents the overall performance, the other bars represent the four sky regions' performances (zenith, south, north, and east-west)



CI.			Per	ez	Brur	nger	ASRC	C-CIE	Matsu	ızawa	Harri	son	Perrau	deau	Kitt	ler
Sky region	Nb Pt.	Lvm	MBD	SD	MBD	SD	MBD	SD	MBD	SD	MBD	SD	MBD	SD	MBD	SD
All sky	153'655	5039	1%	37%	0%	39%	2%	39%	2%	43%	-3%	44%	3%	47%	2%	46%
Zenith	30'966	5025	0%	37%	3%	38%	4%	38%	8%	43%	-1%	43%	-13%	42%	9%	46%
South	28'214	8302	-2%	38%	-3%	40%	-1%	40%	-9%	42%	-13%	45%	13%	47%	-13%	43%
North	30'659	3572	5%	33%	2%	36%	-3%	34%	7%	39%	10%	39%	2%	47%	18%	47%
East-west	63'816	4309	3%	31%	0%	33%	4%	33%	7%	34%	0%	34%	3%	38%	6%	37%

All stations: zeta > 15° without horizon normalized by Dvh.

strument has errors in the positioning of the measurement head. The station of Garston is also equipped with a PRC Krochmann sky scanner.

The study of Table 4 and Fig. 3 shows that the seven models give better results with the Japanese data. The better performance obtained with the Perez model on Berkeley's data is due to the correlation between the data and the model development, and to the luminance integrated value of *Dvh*.

7. CONCLUSION

All the results presented are obtained with limited data banks, covering a small period of the year (no season, humidity, temperature, turbidity, etc., dependencies are considered here), and cannot be taken as representative of the various climates, but the aim of this study was to validate sky luminance distribution data banks. Nevertheless, from the figures and tables, one can see:

- For luminance values far from the sun direction, Koto-Ku's data gave the best results. This may be due to higher atmospheric turbidity (or lower epsilon values) in this data bank.
- As we did not find opaque cloud cover measurements for the tested data, we used a normalized K index (K = Dh/Gh) to apply Harrison's model. The result is a great disparity of the results depending on the data bank.

- The smallest reductions in RMS when the circumsolar region was removed were obtained for the Garston and the Geneva data banks and may be due to the better optical system of the sky scanner: the PRC Krochmann scanner has a sensitivity equal to zero at ±5°, whereas the EKO Instruments scanner's sensitivity is 60% of the maximum at ±5°, going down to zero at ±9° [7]. Such a conclusion cannot be made from Berkeley's data, because all of the nonluminance data (except Bvn) are deduced from luminance measurements.
- According to the significant change in MBE and RMS, when eliminating the horizon band in the Japanese data, we conclude that the station was surrounded by obstructions with nonnegligible height. On the whole, and without the climate's representative data, we obtained similar results, independently of the instrument and the site of measurement. We conclude that the different data banks are comparable.

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NOMENCLATURE

Io, Ivo extraterrestrial irradiance and illuminance on a plane tracking the sun

- Z solar zenith angle
- Ma optical air mass
- Gh, Dh global and diffuse irradiances on a horizontal plane $W \cdot m^{-2}$
 - Bn beam irradiance on a plane tracking the sun $W \cdot m^{-2}$
- Gvh, Dvh global and diffuse illuminances on a horizontal plane lux
 - Bvn beam illuminance on a plane tracking the sun lux
- Lvm, Lvm measured luminance, average Lvm, $cd \cdot m^{-2}$
 - Lvz zenith luminance, cd \cdot m⁻²
 - Kt, Kt' clearness index, enhanced clearness index [16]
 - K, Kv Dh/Gh, Dvh/Gvh
 - zeta angular distance between the considered point and the sun
 - delta Perez' brightness index epsilon Perez' clearness index

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